武汉理工大学2017年申报专业技术岗位任职资格综合表（教学、科研岗位人员用表）

所在单位：自动化学院申报学科：信息学科

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| 姓名 | 庞牧野 | | | | 性别 | | | 男 | | | 职工号 | | 10747 | | | 联系电话 | | | 13971374795 | | | | | 师德、思想政治表现及工作业绩小结 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 出生年月 | 1985.12 | | | | 参加工作  时间 | | | | | | 2015.5 | | | | 现职称及  取得时间 | | 讲师  2015.5 | | | | | | | 教师作为人类灵魂的工程师，需要良好的师德。本人思想积极，进取向上，拥护中国共产党领导，爱岗敬业，无私奉献。以爱国心，事业心，责任心三心为动力，全身心投入教育教学工作，形成自身正确的人生观价值观。同事之间和睦相处，互帮互助。  教学工作中，我不断提升自己的业务水平，并把课前精备、课上精讲、课后精练作为减轻学生负担，提高教学质量的教学三环节，课堂上激发学生自觉参与学习的意识，最大限度地提高单位时间里的教学效益。工作上，我严格要求自己，工作实干，完成学校给予的各项任务。  作为一名老师，我认识将教学与科研工作结合到一起的重要性。随着互联网发展，知识的获取手段越来越多，来源越来越丰富。只是拘泥于陈旧的课本，将很快无法满足学生以及社会的需求。所以，工作以来，我在深入自身研究的同时，将研究内容与教学实践相结合，尽量丰富学生的课堂内容，使他们保持与世界前沿的联系。同时我虚心的听取其他同事的意见，并进行及时的调整。在教学中注意与学生的交流、适时的引导学生，致力于营造快乐课堂，让学生快乐学习并学有所获。 当然，要成为一名合格的教师，不仅要懂得教书，更要懂得育人。因此，在教学的同时，我也很关注学生思想品德的成长，及时引导。  在今后的教研工作中，我会继续努力，虚心求教，提高课堂教学的水平以及科研能力。相信通过我的努力我会不断进步，不断成长。 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 前学历、学位（取得时间、毕业学校、专业） | | | | | | 硕士研究生，硕士，2011  电子科技大学，机械制造及其自动化 | | | | | | | | | | 现从事  专业 | | | 控制理论与控制工程 | | | | |
| 最后学历、学位（取得时间、毕业学校、专业） | | | | | | 博士研究生，博士，2015  日本国立香川大学，智能机械系统 | | | | | | | | | | 党政兼职 | | | 无 | | | | |
| 申报岗位  及类型 | | 副教授 | | | | | | | | | | 近三年考核 | | | | 2014年 | | 2015年 | | | 2016年 | | |
|  | | 不定等次 | | | 合格 | | |
| 主要工作及学术经历 | | 目前主要工作集中于人体踝关节生物力学分析及机器人关节作动器性能研究。  2012/04-2015/03，日本国立香川大学，工学部，博士  2008/09-2011/06，电子科技大学，空天科学技术研究院，硕士  2004/09-2008/06，电子科技大学，机械电子工程学院，学士 | | | | | | | | | | | | | | | | | | | | | |
| 组合条件 | | 教学要求+论文要求（3）+项目和成果要求（3）+选择条件（6） | | | | | | | | | | | | | | | | | | | | | |
| 近五学年（或任现职以来）教学工作 | | 承担本科生课程名称 | | | | | | | | 2015-2016学年：控制系统仿真技术；2016-2017学年：控制系统仿真技术 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 承担研究生课程名称 | | | | | | | | 2014-2015学年：系统建模理论与技术 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | 指导研究生在读/毕业人数 | | | | | | | | 1/0 | | |
| 近五年本科生教学工作总量 | | | | | | | | 246.46 | | | | 近5年研究生教学工作总量 | | | | | | 36 | | | 减免工作量合计 | | | | | 300 | | 年均工作量 | | | | 441.23 | | | 年均课堂教学工作量 | | | | | | | | 35.76 | | | | | 额定工作量 | | | 200 | | |
| 近三学年所有本科课程教学评教分（学年） | | | | | | | | 2015-2016：92.5  2016-2017：90.97 | | | | | | | | | | | | | | | | | | | | | | | | | | 近三年每年教学评教分排序/所在学院副教授人数 | | | | | | | | |  | | | | | | | | | | |
| 优质优酬课程 | | | | | | | |  | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 主持教研项目 | | | | | | | |  | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 教学成果奖 | | | | | | | |  | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 教学工程项目 | | | | | | | |  | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 近五学年（或任现职以来）承担的科研项目情况 | | 序号 | 课题编号 | | | | | | | 课题名称 | | | | | | | | | 任务来源 | | | | | | 来源分类 | | | | 项目级别 | | | | 主持/参与 | | | | | | 合同经费 | | | | | 累计到款 | | | | 个人分解  研究经费 | | | | | | | 备注 |
| 1 | 20161j0080 | | | | | | | 仿肌肉反射的双足机器人直立抗扰策略研究 | | | | | | | | | 国家自然科学基金 | | | | | | 青年科学基金项目 | | | | 国家级 | | | | 主持 | | | | | | 20 | | | | | 12 | | | | 12 | | | | | | |  |
| 2 | 20151f0012 | | | | | | | 201511HX02 | | | | | | | | | JGXM | | | | | | 军工横向 | | | |  | | | | 参与 | | | | | | 78 | | | | | 78 | | | | 10 | | | | | | |  |
| 3 | 20151j0155 | | | | | | | 多模态人手手内操作技巧研究及其在仿生机械手上的应用 | | | | | | | | | 国家自然科学基金 | | | | | | 面上项目 | | | | 国家级 | | | | 参与 | | | | | | 73.8 | | | | | 55.8 | | | | 5 | | | | | | |  |
| 4 |  | | | | | | |  | | | | | | | | |  | | | | | |  | | | |  | | | |  | | | | | |  | | | | |  | | | |  | | | | | | |  |
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| 任现职以来发表论文 | | 序号 | 论文名称 | | | | | | | | | | | | | | | | | | | 期刊名称 | | | | | 年卷期页 | | | | | 刊号 | | | | | | 作者排序 | | | | 是否国际会议论文集 | | | | 分区 | | | 检索/转载 | | | 备注 | | | |
| 1 | Comparison of sEMG based Feature Extraction and Motion Classification Methods for Upper-limb Movement | | | | | | | | | | | | | | | | | | | Sensors | | | | | 2015年15卷4期：9022-9038 | | | | | 1424-8220 | | | | | | 2（通信，导师第一作者） | | | | 否 | | | | 国际A区 | | | SCI | | |  | | | |
| 2 | 基于表面肌电的人体与环境交互力预测 | | | | | | | | | | | | | | | | | | | 华中科技大学学报(自然科学版) | | | | | 2015年43卷s1期：372-375(380) | | | | | 1671-4512 | | | | | | 1 | | | | 否 | | | | 国内A区 | | | EI | | |  | | | |
| 3 | Prediction of Interaction Force using EMG for Characteristic Evaluation of Touch and Push Motions | | | | | | | | | | | | | | | | | | | IEEE/RSJ International Conference on Intelligent Robots and Systems | | | | | 2015：2099-2104 | | | | | 2153-0858 | | | | | | 1 | | | | 是 | | | | 国内C区 | | | EI | | |  | | | |
| 4 | Interaction force transfer for characteristic evaluation of touch motion | | | | | | | | | | | | | | | | | | | 2014 IEEE International Conference on Mechatronics and Automation | | | | | 2014：1237-1242 | | | | | 9781479939787 | | | | | | 1 | | | | 是 | | | | 国内C区 | | | EI | | |  | | | |
| 5 | Electromyography-BasedQuantitativeRepresentationMethodforUpper-LimbElbowJointAngleinSagittalPlane | | | | | | | | | | | | | | | | | | | Journal of Medical and Biological Engineering | | | | | 2015年35卷2期：165-177 | | | | | 1609-0985 | | | | | | 1 | | | | 否 | | | | 国际C区 | | | SCI | | | 选择条件用 | | | |
| 6 |  | | | | | | | | | | | | | | | | | | |  | | | | |  | | | | |  | | | | | |  | | | |  | | | |  | | |  | | |  | | | |
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| 折算论文 | | | | |  | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 论文小计 | | | | | 例：国际A区1，SCI2，EI3，国内A区1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 近五学年（或任现职以来）获得科技奖励情况 | | 序号 | | 获奖编号 | | | | | 获奖名称 | | | | | | | | | | | | | | | | | 奖励名称 | | | | | 评奖单位 | | | | 获奖时间 | | | | | | 人员排名 | | 奖励级别 | | | | 奖励等级 | | | | 单位排名 | | | 证书编号 | |
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| 近五学年（或任现职以来）专利权转让收益情况 | | 序号 | | 专利号 | | | | | 专利名称 | | | | | | | | | | | | | | | | | 转让时间 | | | | | 转让单位名称 | | | | | | | | | | | | | | | | 转让收益（万元） | | | | | | | 备注 | |
|  | |  | | | | |  | | | | | | | | | | | | | | | | |  | | | | |  | | | | | | | | | | | | | | | |  | | | | | | |  | |
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| 教学科研业绩选择条件情况 | | 序号 | | 成果简况 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | 细则规定 | | | | | | | | | | | | | | | |
| 1 | | Muye Pang, ShuxiangGuo, Hidenori Ishihara, Hideyuki Hirata, Electromyography-Based Quantitative Representation Method for Upper-Limb Elbow Joint Angle in Sagittal Plane, Journal of Medical and Biological Engineering(SCI), Vol 35, No. 2, pp 165-177, 2015. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | （6）以第一发明人身份获国家发明专利1项且专利在有效期内，或发表SCI收录论文1篇及以上。 | | | | | | | | | | | | | | | |
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| 本人承诺所填写和提供的材料、内容均真实有效。  申报人（手写签名）：  2017年月日 | | | | | | | | | | | | | | | | | | | | | | | | | | 单位审核推荐意见：  （公章）  院长/主任（签字）： 2017年月日 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |